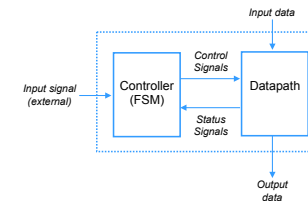


Lecture 6 Algorithmic State Machines (ASMs)

Control and Datapath Interaction

- Binary information in digital system can be classified into two categories
- Data
 - Discrete elements of information manipulated by arithmetic, logic, shift, and other data processing
 - Operations implemented via digital components such as adders, decoders, muxes, etc.
- Control
 - Provides command signals that coordinate the execution of various operations in data section to accomplish desired task



What Control Path Implements?

- Sequencing of control signals to execute algorithm implemented by circuit
- Algorithm
 - Finite set of instructions/steps to solve a problem
 - Terminates in finite time at a known end state
- Many representations

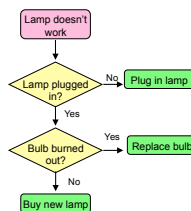
Ingredients

- 1/3 cup unsweetened cocoa
- 1/4 cup cornstarch
- 2 tablespoons butter
- 2 2/3 cups skim milk

Steps

- Combine all ingredients in a small saucepan. Heat over low heat, stirring constantly, until mixture boils. Boil gently, stirring constantly, for one minute.
- Pour into serving dishes and chill until thickened.

Recipe



Flowchart

```
int fib(int n)
{
    if (n < 2)
        return n;
    else
        return fib(n-1) + fib(n-2);
}
```

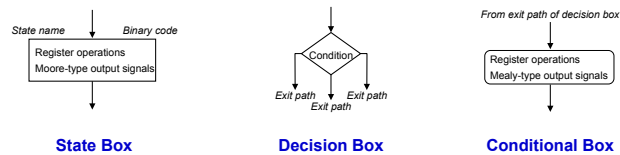
Computer Program

Flowcharts and Algorithmic State Machines (ASM)

- Flowchart
 - Convenient way to graphically specify sequence of procedural steps and decision paths for algorithm
 - Enumerates sequence of operations and conditions necessary for execution
- Algorithmic State Machine (ASM)
 - Flowchart defined specifically for digital hardware algorithms
- Flowchart vs. ASM
 - Conventional flowchart
 - Sequential way of representing procedural steps and decision paths for algorithm
 - No time relations incorporated
 - ASM chart
 - Representation of sequence of events together with timing relations between states of sequential controller and events occurring while moving between steps

ASM Chart

- Three basic elements
 - State box
 - Decision box
 - Conditional box
- State and decision boxes used in conventional flowcharts
 - Conditional box characteristic to ASM

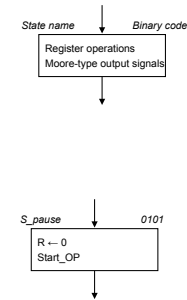


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State box

- Used to indicate states in control sequence
 - State name and binary code placed on top of box
 - Register operations and names of output signals generated in state placed inside box
- Example
 - State name: S_pause
 - Binary encoding: 0101
 - Register operation: $R \leftarrow 0$
 - Register R is to be cleared to 0
 - Output signal asserted: Start_OP = 1
 - Launches some operation in datapath

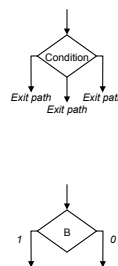


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Decision Box

- Reflects the effect of an input
 - external or internal, input or status
- Diamond shaped box
 - Condition to be tested inside
 - Two or more outputs represent exit paths dependent on value tested
 - In binary case one path represents true the other false, represented by 1 and 0 respectively
- Example
 - Check B
 - If B is true (=1), take path marked 1
 - If B is false (=0), take path marked 0

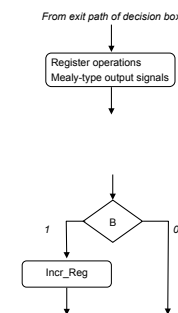


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Conditional Box

- Unique to ASM
- Inputs come from one of exit paths of decision boxes
- Register operation or outputs listed inside box generated during given state
 - Generated as Mealy-type signals
 - Associated with the state transition
- Example
 - Status of input B checked
 - Conditional operation executed depending on result coming from decision box
 - If B = 1, assert Incr_Reg signal
 - Otherwise Incr_Reg remains unchanged

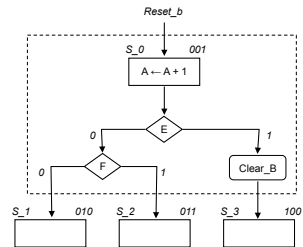


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ASM Block

- Structure consisting of
 - One state box
 - All decision and conditional boxes associated with its exit paths
- Block has one entrance and any number of exits paths
- Each block in ASM dedicated to state of system during one clock cycle
- Simplifications
 - ASM Block not usually drawn because blocks are well defined
 - Can label just the "1" and omit the "0"
- ASM chart consists of one or more interconnect ASM Blocks

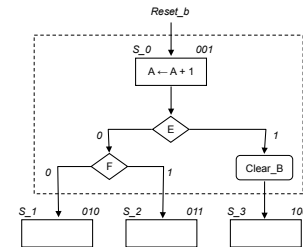


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Interpretation of Timing Operations

- Conventional flowchart, evaluation of each follows one another
 - Reg A incremented
 - Condition E evaluated
 - If E = 1
 - clear B
 - Go to state S₃
- In ASM the entire block considered as one unit
 - All operations within block occurring during single edge transition
 - The next state evaluated during the same clock
 - System enters next state S₁, S₂, or S₃ during transition of next clock



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ASM Example

- Convert pseudo code to ASM chart
- Example
 - Want to detect the number of 1's in a 2-bit register called *Input*
 - start* input indicates when to begin comparison
 - busy* output indicates when comparison in progress
 - ones* hold count value
 - F* outputs result

```

S0:
  busy = 0;
  ones = 0;

  if(start == 1)
    goto S1
  else
    goto S0

S1:
  busy = 1;
  if(Input[1] == 1)
    ones ++;
  goto S2

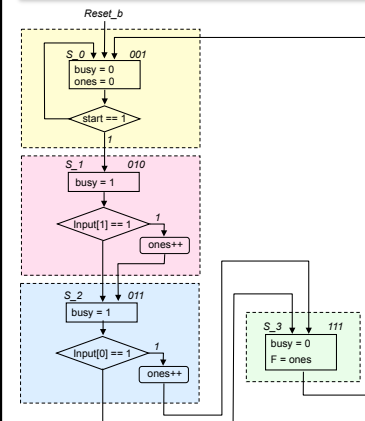
S2:
  busy = 1;
  if(Input[0] == 1)
    ones ++;
  goto S3

S3:
  busy = 0;
  F = ones;
  goto S0
    
```

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ASM Example Continued



```

S0:
  busy = 0;
  ones = 0;

  if(start == 1)
    goto S1
  else
    goto S0

S1:
  busy = 1;
  if(Input[1] == 1)
    ones ++;
  goto S2

S2:
  busy = 1;
  if(Input[0] == 1)
    ones ++;
  goto S3

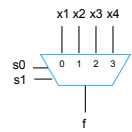
S3:
  busy = 0;
  F = ones;
  goto S0
    
```

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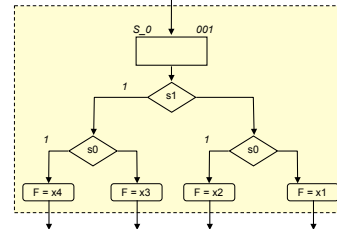
ASM – Mux

- Describe a 4x1 MUX using a ASM



4x1 mux

s1	s0	f
0	0	x1
0	1	x2
1	0	x3
1	1	x4

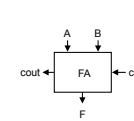


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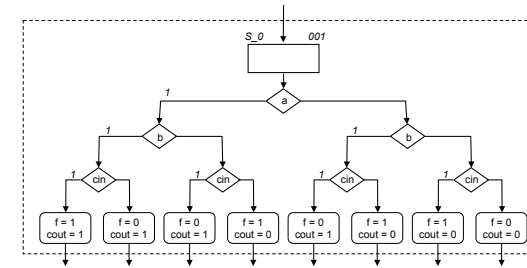
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ASM – Full Adder

- Describe a 1-bit full adder using an ASM chart



a	b	cin	f	cout
0	0	0	0	0
0	0	1	1	0
0	1	0	1	0
0	1	1	0	1
1	0	0	1	0
1	0	1	0	1
1	1	0	0	1
1	1	1	1	1



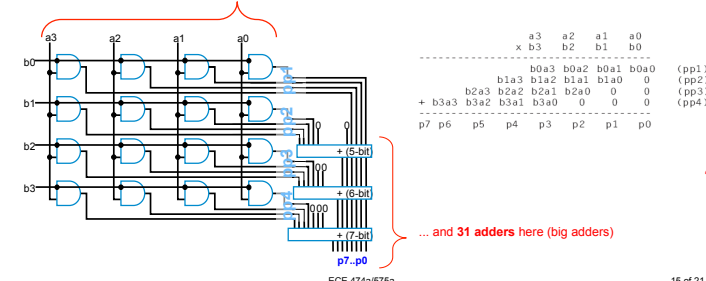
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Smaller Multiplier

- Multiplier in array style
 - Fast, reasonable size for 4-bit: $4*4 = 16$ partial product AND terms, 3 adders
 - Rather big for 32-bit: $32*32 = 1024$ AND terms, and 31 adders

32-bit adder would have 1024 gates here

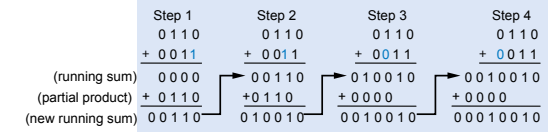


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Smaller Multiplier -- Sequential (Add-and-Shift) Style

- Smaller multiplier: Basic idea
 - Don't compute all partial products simultaneously
 - Rather, compute one at a time (similar to by hand), maintain running sum

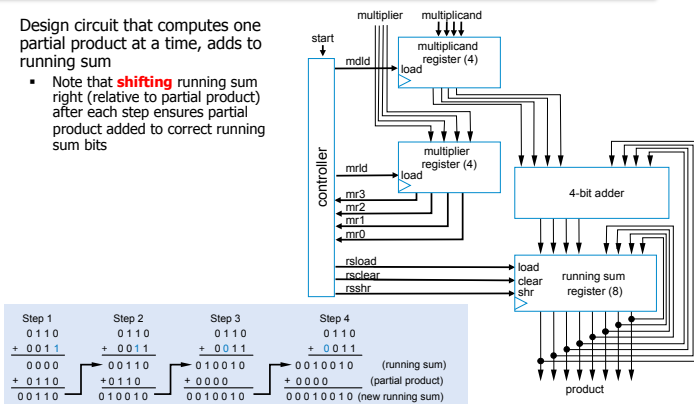


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Smaller Multiplier -- Sequential (Add-and-Shift) Style

- Design circuit that computes one partial product at a time, adds to running sum
 - Note that **shifting** running sum right (relative to partial product) after each step ensures partial product added to correct running sum bits



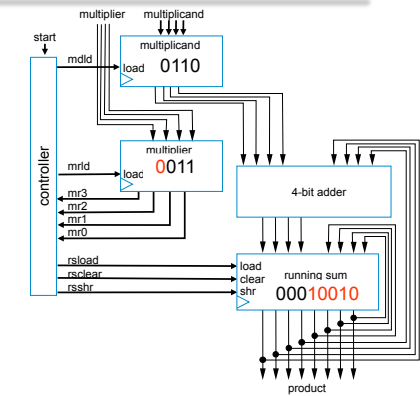
Step 1	Step 2	Step 3	Step 4
0110	0110	0110	0110
+ 0011	+ 0011	+ 0011	+ 0011
0000	00110	010010	0010010
+ 0110	+ 0110	+ 0000	+ 0000
00110	010010	0010010	00010010
			(new running sum)

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Smaller Multiplier -- Sequential (Add-and-Shift) Style

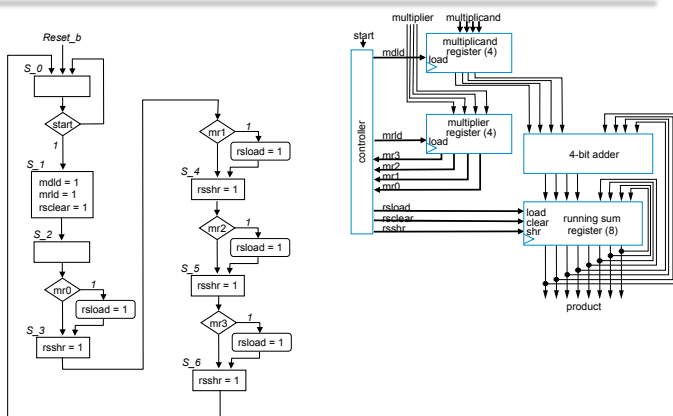
- Step 0**
 - Set running sum to 0
 - Load values
- Step 1**
 - Check multiplier bit 0 (mr0)
 - mr0=1, add multiplicand to running sum
 - Shift running sum right 1 position
- Step 2**
 - Check multiplier bit 1 (mr1)
 - mr0=1, add multiplicand to running sum
 - Shift running sum right 1 position
- Step 3**
 - Check multiplier bit 2 (mr2)
 - mr0=1, add multiplicand to running sum
 - Shift running sum right 1 position
- Step 4**
 - Check multiplier bit 3 (mr3)
 - mr0=1, add multiplicand to running sum
 - Shift running sum right 1 position



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ASM – Sequential Multiplier

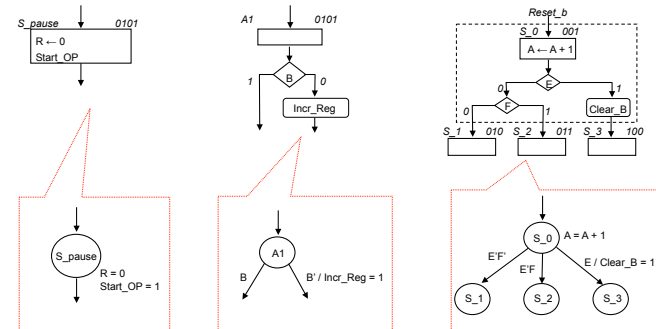


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ASMs to FSMDs

- Able to convert between formats
- Once we have a FSMD, we've already seen how to implement in hardware



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Not Used Much, But ...

- There are commercial ASM Editors
 - Mentor Graphics
 - Summit Design, Inc.
 - Others...

