

ECE 274 Digital Logic

Datapath Components – Multifunction Registers

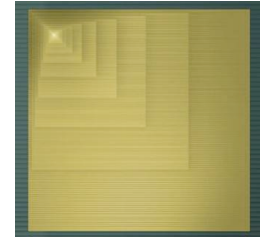
Digital Design 4.1 – 4.2



Digital Design

Chapter 4: Datapath Components

Slides to accompany the textbook *Digital Design*, First Edition,
by Frank Vahid, John Wiley and Sons Publishers, 2007.
<http://www.dvvhid.com>



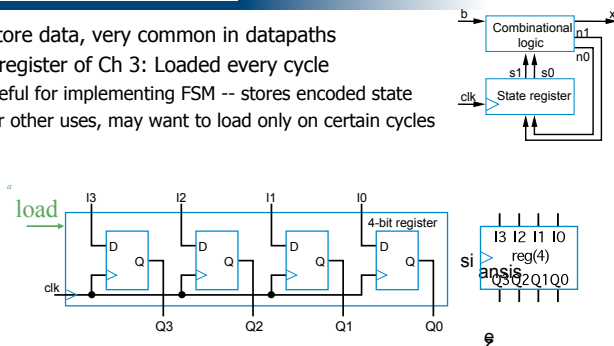
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Datapath Components Registers

4.2

- Can store data, very common in datapaths
- Basic register of Ch 3: Loaded every cycle
 - Useful for implementing FSM -- stores encoded state
 - For other uses, may want to load only on certain cycles

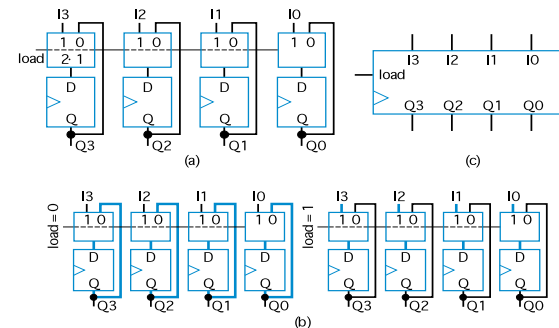


Basic register loads on every clock cycle
How extend to only load on certain cycles?

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Datapath Components Register with Parallel Load

- Add 2x1 mux to front of each flip-flop
- Register's load input selects mux input to pass
 - Either existing flip-flop value, or new value to load



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Datapath Components

Register Example: Above-Mirror Display



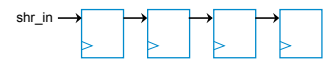
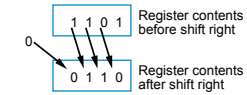
- Instead of connecting car's computer to display using 32 wires, can we use fewer wires?
- To reduce wires: Car's computer can write 1 value at a time, loads into one of four registers with display

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Datapath Components

Shift Registers

- Shift right
 - Move each bit one position right
 - Shift in 0 to leftmost bit
- Shift Register
 - Connect register's flip-flop's outputs to next flip-flop's input
 - This design would always shift on every clock cycle
 - How can we control it?

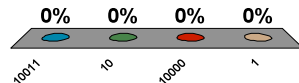


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Datapath Components

Shift Registers

- What is the result after shifting 10011 four times to the right?
 1. 10011
 2. 00010
 3. 10000
 4. 00001

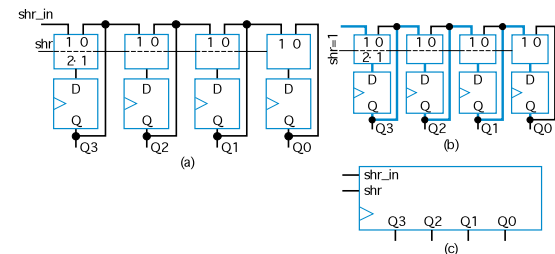


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Datapath Components

Shift Register

- To allow register to either shift or retain, use 2x1 muxes
 - shr: 0 means retain, 1 shift
 - shr_in: value to shift in
 - May be 0, or 1
- Note: Can easily design shift register that shifts left instead

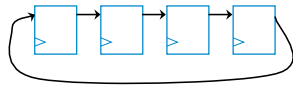
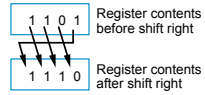


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Datapath Components

Rotate Register

- Rotate right
 - Like shift right, but leftmost bit comes from rightmost bit



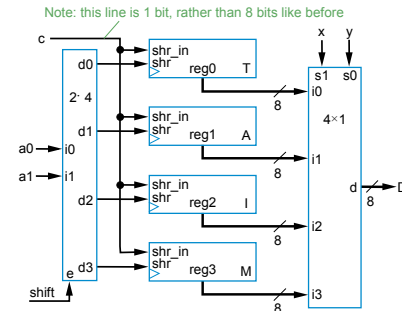
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Datapath Components

Shift Register Example: Above-Mirror Display



- Earlier example: 8 + 2 + 1 = 11 wires from car's computer to above-mirror display's four registers
 - Better than 32 wires, but 11 still a lot -- want fewer for smaller wire bundles
- Use shift registers
 - Wires: 1 + 2 + 1 = 4
 - Computer sends one value at a time, one bit per clock cycle



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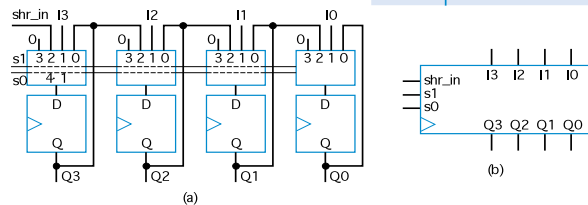
Datapath Components

Multifunction Registers

- Many registers have multiple functions
 - Load, shift, clear (load all 0s)
 - And retain present value, of course
- Easily designed using muxes
 - Just connect each mux input to achieve desired function

Functions:

s1	s0	Operation
0	0	Maintain present value
0	1	Parallel load
1	0	Shift right
1	1	(unused - let's load 0s)

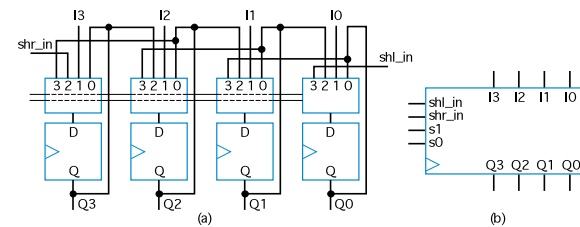


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Datapath Components

Multifunction Registers

s1	s0	Operation
0	0	Maintain present value
0	1	Parallel load
1	0	Shift right
1	1	Shift left



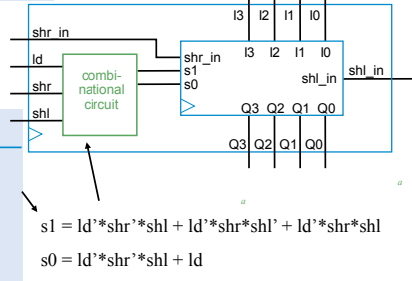
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Datapath Components Multifunction Registers with Separate Control Inputs

ld	shr	shl	Operation
0	0	0	Maintain present value
0	0	1	Shift left
0	1	0	Shift right
0	1	1	Shift right – shr has priority over shl
1	0	0	Parallel load
1	0	1	Parallel load – ld has priority
1	1	0	Parallel load – ld has priority
1	1	1	Parallel load – ld has priority

Truth table for combinational circuit

Inputs	ld	shr	shl	Outputs	s1	s0	Note	Operation
0	0	0	0	0	0	0		Maintain value
0	0	0	1	1	1	1		Shift left
0	0	1	0	1	0	0		Shift right
0	1	1	1	1	0	0		Shift right
1	0	0	0	0	1	1		Parallel load
1	0	1	0	0	1	0		Parallel load
1	1	0	0	0	1	0		Parallel load
1	1	1	0	0	1	0		Parallel load



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Datapath Components Register Operation Table

- Register operations typically shown using compact version of table
 - X means same operation whether value is 0 or 1
 - One X expands to two rows
 - Two Xs expand to four rows
 - Put highest priority control input on left to make reduced table simple

Inputs			Outputs		Note	Operation
ld	shr	shl	s1	s0		
0	0	0	0	0		Maintain value
0	0	1	1	1		Shift left
0	1	0	1	0		Shift right
0	1	1	1	0		Shift right
1	0	0	0	1		Parallel load
1	0	1	0	1		Parallel load
1	1	0	0	1		Parallel load
1	1	1	0	1		Parallel load

ld	shr	shl	Operation
0	0	0	Maintain value
0	0	1	Shift left
0	1	X	Shift right
1	X	X	Parallel load

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Datapath Components Register Design Process

- Can design register with desired operations using simple four-step process

TABLE 4.1 Four-step process for designing a multifunction register.

Step	Description
1. Determine mux size	Count the number of operations (don't forget the maintain present value operation!) and add in front of each flip-flop a mux with at least that number of inputs.
2. Create mux operation table	Create an operation table defining the desired operation for each possible value of the mux select lines.
3. Connect mux inputs	For each operation, connect the corresponding mux data input to the appropriate external input or flip-flop output (possibly passing through some logic) to achieve the desired operation.
4. Map control lines	Create a truth table that maps external control lines to the internal mux select lines, with appropriate priorities, and then design the logic to achieve that mapping

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Datapath Components Register Design Example

- Desired register operations
 - Load, shift left, synchronous clear, synchronous set

s2	s1	s0	Operation
0	0	0	Maintain present value
0	0	1	Parallel load
0	1	0	Shift left
0	1	1	Synchronous clear
1	0	0	Synchronous set
1	0	1	Maintain present value
1	1	0	Maintain present value
1	1	1	Maintain present value

Step 1: Determine mux size

5 operations: above, plus maintain present value (don't forget this one!)
-> Use 8x1 mux

Step 2: Create mux operation table

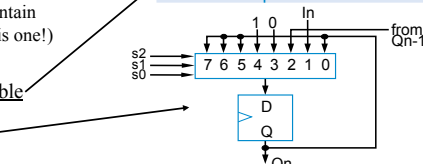
Step 3: Connect mux inputs

Step 4: Map control lines

$$s2 = clr * set$$

$$s1 = clr * set * ld * shl + clr$$

$$s0 = clr * set * ld + clr$$

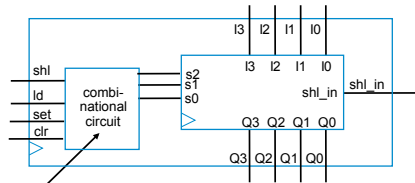


Inputs			Outputs			Operation
clr	set	ld	s2	s1	s0	
0	0	0	0	0	0	Maintain present value
0	0	0	1	0	1	Shift left
0	0	1	X	0	0	Parallel load
0	1	X	X	1	0	Set to all 1s
1	X	X	X	0	1	Clear to all 0s

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Datapath Components

Register Design Example



Step 4: Map control lines

$$s2 = \text{clr}' * \text{set}$$

$$s1 = \text{clr}' * \text{set}' * \text{ld}' * \text{shl} + \text{clr}$$

$$s0 = \text{clr}' * \text{set}' * \text{ld} + \text{clr}$$

Inputs	Inputs			Outputs			Operation
	clr	set	ld	shl	s2	s1	
0	0	0	0	0	0	0	Maintain present value
0	0	0	1	0	1	0	Shift left
0	0	1	X	0	0	1	Parallel load
0	1	X	X	1	0	0	Set to all 1s
1	X	X	X	0	1	1	Clear to all 0s