

ECE 274 Digital Logic

RTL Design – Memories and Hierarchy

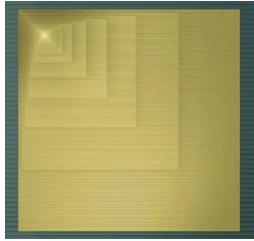
Digital Design 5.6 – 5.8



THE UNIVERSITY OF
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Digital Design

Chapter 5: RTL Design



Slides to accompany the textbook *Digital Design*, First Edition,
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RTL Design

RTL Design Method

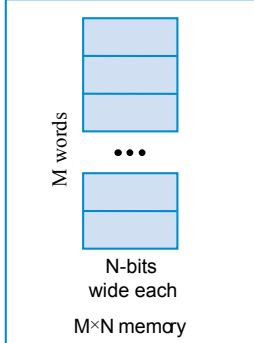
Step	Description
Step 1 <i>Capture a high-level state machine</i>	Describe the system's desired behavior as a high-level state machine. The state machine consists of states and transitions. The state machine is "high-level" because the transition conditions and the state actions are more than just Boolean operations on bit inputs and outputs.
Step 2 <i>Create a datapath</i>	Create a datapath to carry out the data operations of the high-level state machine.
Step 3 <i>Connect the datapath to a controller</i>	Connect the datapath to a controller block. Connect external Boolean inputs and outputs to the controller block.
Step 4 <i>Derive the controller's FSM</i>	Convert the high-level state machine to a finite-state machine (FSM) for the controller, by replacing data operations with setting and reading of control signals to and from the datapath.

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Memory Components

- Register-transfer level design instantiates datapath components to create datapath, controlled by a controller
 - A few more components are often used outside the controller and datapath
- *MxN memory*
 - M words, N bits wide each
- Several varieties of memory, which we now introduce



M words

N-bits wide each

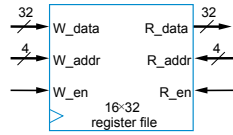
M×N memory

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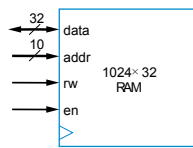
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Random Access Memory (RAM)

- RAM – Readable and writable memory
 - “Random access memory”
 - Strange name – Created several decades ago to contrast with sequentially-accessed storage like tape drives
 - Logically same as register file – Memory with address inputs, data inputs/outputs, and control
 - RAM usually just one port; register file usually two or more
 - RAM vs. register file
 - RAM typically larger than *roughly* 512 or 1024 words
 - RAM typically stores bits using a bit storage approach that is more efficient than a flip flop
 - RAM typically implemented on a chip in a square rather than rectangular shape – keeps longest wires (hence delay) short



Register file from Chpt. 4

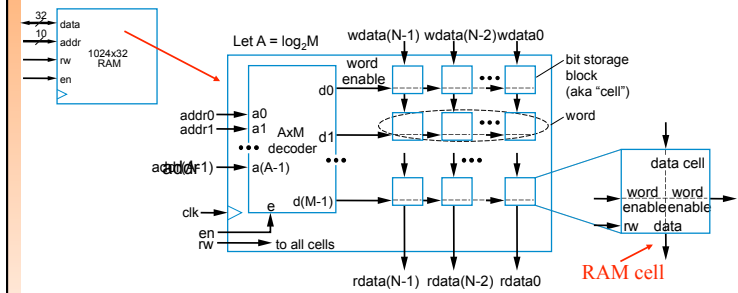


RAM block symbol

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RAM Internal Structure

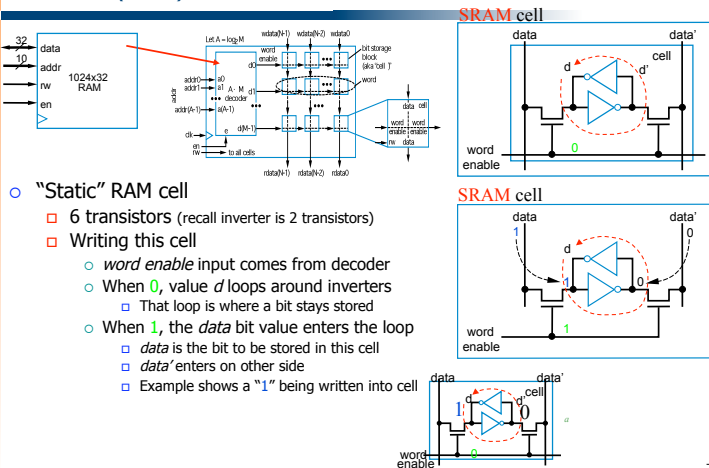


- Similar internal structure as register file
 - Decoder enables appropriate word based on address inputs
 - rw controls whether cell is written or read
 - Let's see what's inside each RAM cell

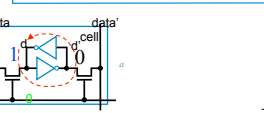
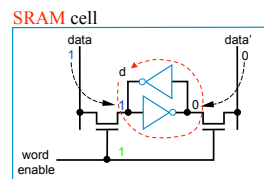
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Static RAM (SRAM)



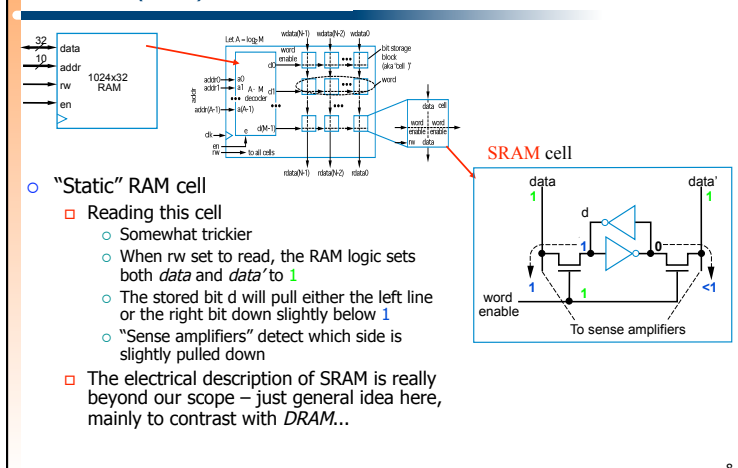
- “Static” RAM cell
 - 6 transistors (recall inverter is 2 transistors)
 - Writing this cell
 - word enable input comes from decoder
 - When 0, value *d* loops around inverters
 - That loop is where a bit stays stored
 - When 1, the *data* bit value enters the loop
 - data* is the bit to be stored in this cell
 - data'* enters on other side



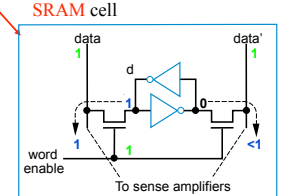
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Static RAM (SRAM)



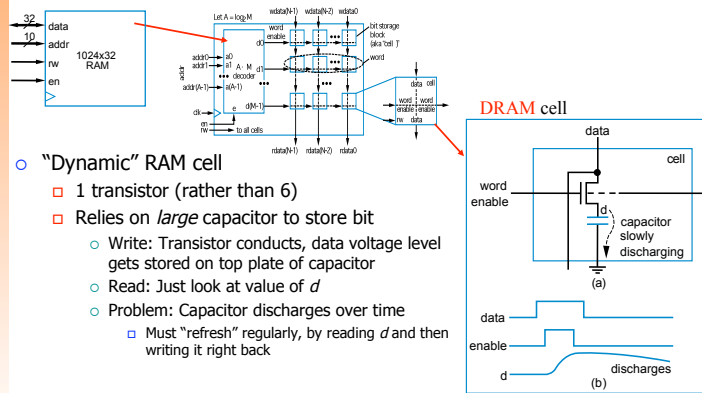
- “Static” RAM cell
 - Reading this cell
 - Somewhat trickier
 - When rw set to read, the RAM logic sets both *data* and *data'* to 1
 - The stored bit *d* will pull either the left line or the right bit down slightly below 1
 - “Sense amplifiers” detect which side is slightly pulled down
 - The electrical description of SRAM is really beyond our scope – just general idea here, mainly to contrast with *DRAM*...



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Dynamic RAM (DRAM)



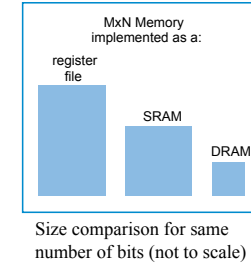
- "Dynamic" RAM cell
 - 1 transistor (rather than 6)
 - Relies on *large* capacitor to store bit
 - Write: Transistor conducts, data voltage level gets stored on top plate of capacitor
 - Read: Just look at value of *d*
 - Problem: Capacitor discharges over time
 - Must "refresh" regularly, by reading *d* and then writing it right back

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Comparing Memory Types

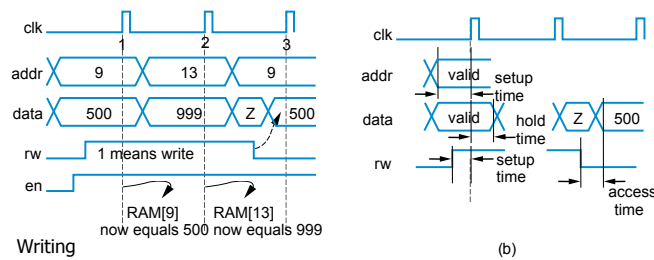
- Register file
 - Fastest
 - But biggest size
- SRAM
 - Fast
 - More compact than register file
- DRAM
 - Slowest
 - And refreshing takes time
 - But very compact
- Use register file for small items, SRAM for large items, and DRAM for huge items
 - Note: DRAM's big capacitor requires a special chip design process, so DRAM is often a separate chip



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Reading and Writing a RAM

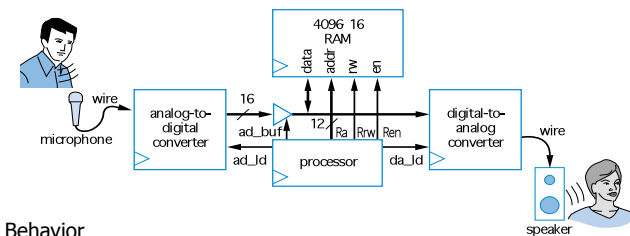


- Writing
 - Put address on *addr* lines, data on *data* lines, set *rw=1*, *en=1*
- Reading
 - Set *addr* and *en* lines, but put nothing (Z) on *data* lines, set *rw=0*
 - Data will appear on *data* lines
- Don't forget to obey setup and hold times
 - In short – keep inputs stable before and after a clock edge

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RAM Example: Digital Sound Recorder



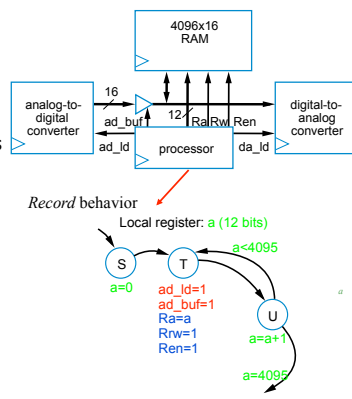
- Behavior
 - Record: Digitize sound, store as series of 4096 12-bit digital values in RAM
 - We'll use a 4096x16 RAM (12-bit wide RAM not common)
 - Play back later
 - Common behavior in telephone answering machine, toys, voice recorders
- To record, processor should read a-to-d, store read values into successive RAM words
 - To play, processor should read successive RAM words and enable d-to-a

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RAM Example: Digital Sound Recorder

- RTL design of processor
 - Create high-level state machine
 - Begin with the *record* behavior
 - Keep local register *a*
 - Stores current address, ranges from 0 to 4095 (thus need 12 bits)
 - Create state machine that counts from 0 to 4095 using *a*
 - For each *a*
 - Read analog-to-digital conv.
 - $ad_ld=1, ad_buf=1$
 - Write to RAM at address *a*
 - $Ra=a, Rrw=1, Ren=1$

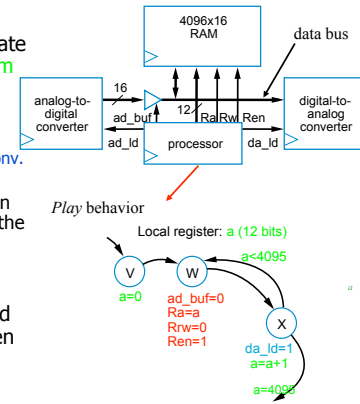


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RAM Example: Digital Sound Recorder

- Now create *play* behavior
- Use local register *a* again, create state machine that counts from 0 to 4095 again
 - For each *a*
 - Read RAM
 - $Ra=a, Rrw=0, Ren=1$
 - Write to digital-to-analog conv.
 - $da_ld=1, a=a+1$
 - Note: Must write d-to-a one cycle *after* reading RAM, when the read data is available on the data bus
- The record and play state machines would be parts of a larger state machine controlled by signals that determine when to record or play

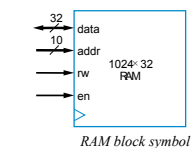


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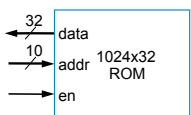
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Read-Only Memory – ROM

- Memory that can only be read from, not written to
 - Data lines are output only
 - No need for *rw* input
- Advantages over RAM
 - Compact: May be smaller
 - **Nonvolatile**: Saves bits even if power supply is turned off
 - Speed: May be faster (especially than DRAM)
 - Low power: Doesn't need power supply to save bits, so can extend battery life
- Choose ROM over RAM if stored data won't change (or won't change often)
 - For example, a table of Celsius to Fahrenheit conversions in a digital thermometer



RAM block symbol



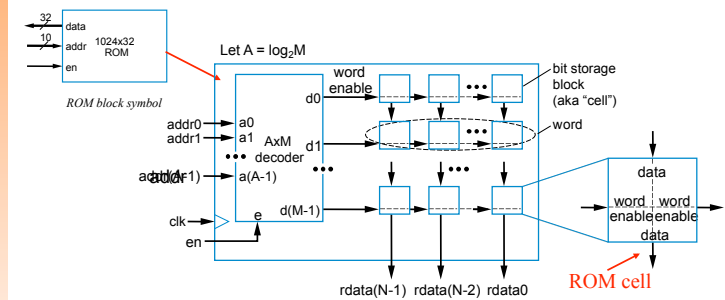
ROM block symbol

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Read-Only Memory – ROM

- Internal logical structure similar to RAM, without the data input lines

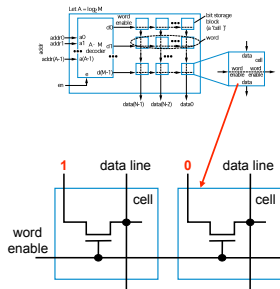


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ROM Types

- If a ROM can only be read, how are the stored bits stored in the first place?
 - Storing bits in a ROM known as *programming*
 - Several methods
- **Mask-programmed ROM**
 - Bits are hardwired as 0s or 1s during chip manufacturing
 - 2-bit word on right stores "10"
 - word enable (from decoder) simply passes the hardwired value through transistor
 - Notice how compact, and fast, this memory would be

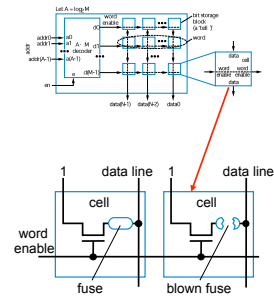


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ROM Types

- **Fuse-Based Programmable ROM**
 - Each cell has a fuse
 - A special device, known as a programmer, blows certain fuses (using higher-than-normal voltage)
 - Those cells will be read as 0s (involving some special electronics)
 - Cells with unblown fuses will be read as 1s
 - 2-bit word on right stores "10"
 - Also known as **One-Time Programmable (OTP) ROM**

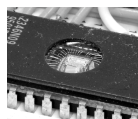
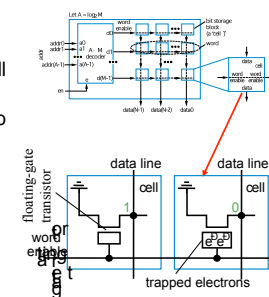


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ROM Types

- **Erasable Programmable ROM (EPROM)**
 - Uses "floating-gate transistor" in each cell
 - Special programmer device uses higher-than-normal voltage to cause electrons to *tunnel* into the gate
 - Electrons become trapped in the gate
 - Only done for cells that should store 0
 - Other cells (without electrons trapped in gate) will be 1
 - 2-bit word on right stores "10"
 - Details beyond our scope – just general idea is necessary here
 - To erase, shine ultraviolet light onto chip
 - Gives trapped electrons energy to escape
 - Requires chip package to have window

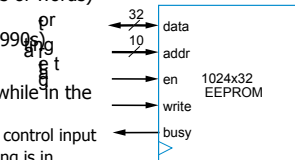


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ROM Types

- **Electrically-Erasable Programmable ROM (EEPROM)**
 - Similar to EPROM
 - Uses floating-gate transistor, electronic programming to trap electrons in certain cells
 - But erasing done *electronically*, not using UV light
 - Erasing done one word at a time
- **Flash memory**
 - Like EEPROM, but all words (or large blocks of words) can be erased *simultaneously*
 - Become common relatively recently (late 1990s)
- Both types are in-system programmable
 - Can be programmed with new stored bits while in the system in which the ROM operates
 - Requires bi-directional data lines, and write control input
 - Also need busy output to indicate that erasing is in progress – erasing takes some time

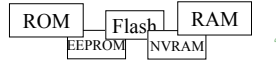


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Blurring of Distinction Between ROM and RAM

- We said that
 - RAM is readable and writable
 - ROM is read-only
- But some ROMs act almost like RAMs
 - EEPROM and Flash are in-system programmable
 - Essentially means that writes are slow
 - Also, number of writes may be limited (perhaps a few million times)
- And, some RAMs act almost like ROMs
 - Non-volatile RAMs: Can save their data without the power supply
 - One type: Built-in battery, may work for up to 10 years
 - Another type: Includes ROM backup for RAM – controller writes RAM contents to ROM before turning off
- New memory technologies evolving that merge RAM and ROM benefits
 - e.g., MRAM
- Bottom line
 - Lot of choices available to designer, must find best fit with design goals

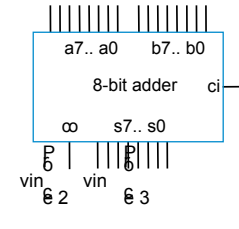


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Hierarchy and Abstraction

- Hierarchy helps us **manage complexity**
 - To go from transistors to gates, muxes, decoders, registers, ALUs, controllers, datapaths, memories, queues, etc.
 - Imagine trying to comprehend a controller and datapath at the level of gates
- Abstraction
 - Hierarchy often involves not just grouping items into a new item, but also associating higher-level behavior with the new item, known as **abstraction**
 - e.g., an 8-bit adder has an understandable high-level behavior – it adds two 8-bit binary numbers
 - Frees designer from having to remember, for even from having to understand, the lower-level details

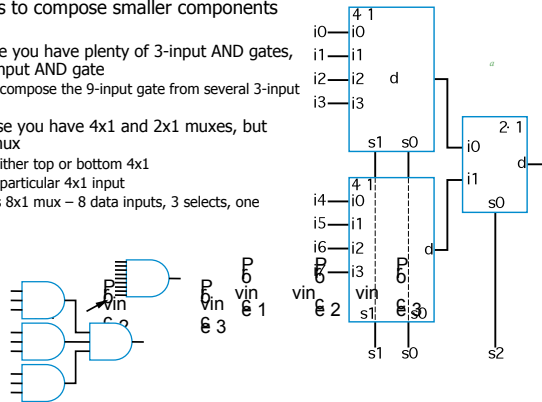


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Hierarchy and Composing Larger Components from Smaller Versions

- A common task is to compose smaller components into a larger one
 - Gates: Suppose you have plenty of 3-input AND gates, but need a 9-input AND gate
 - Can simple compose the 9-input gate from several 3-input gates
 - Muxes: Suppose you have 4x1 and 2x1 muxes, but need an 8x1 mux
 - s2 selects either top or bottom 4x1
 - s1s0 select particular 4x1 input
 - Implements 8x1 mux – 8 data inputs, 3 selects, one output

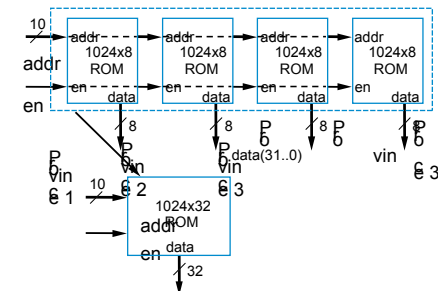


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Hierarchy and Composing Larger Components from Smaller Versions

- Composing memory very common
- Making memory words wider
 - Easy – just place memories side-by-side until desired width obtained
 - Share address/control lines, concatenate data lines
 - Example: Compose 1024x8 ROMs into 1024x32 ROM



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Hierarchy and Composing Larger Components from Smaller Versions

- Creating memory with more words
 - Put memories on top of one another until the number of desired words is achieved
 - Use decoder to select among the memories
 - Can use highest order address input(s) as decoder input
 - Although actually, any address line could be used
 - Example: Compose 1024x8 memories into 2048x8 memory

